



A GENERALIZED CLOSED SETS IN TOPOLOGICAL SPACES

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ABSTRACT

In this paper, we introduce and study a new class of sets namely \bar{g} -closed sets which settled in between the class of closed sets and the class of g-closed sets and then we study many basic properties of \bar{g} -closed set together with the relationships of some other sets.

As applications of \bar{g} -closed sets, we introduce some new separation properties, namely \bar{T} -spaces, \bar{T}^* -spaces and ${}^*\bar{T}$ -spaces and then discuss some of their properties. Further we introduce and study new types of continuity namely \bar{g} -continuity and \bar{g} -irresoluteness.

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INTRODUCTION

The study of g-closed sets in a topological space was initiated by Levine [3] in 1970. Levine [1] also introduced the concept of semi-open sets and semi-continuity in topological spaces in 1963. Bhattacharya and Lahiri [7] introduced sg-closed sets in 1987. Arya and Nour [8] defined gs-closed sets in 1990. N. jasted [2] introduced the concepts of α -closed sets for topological spaces in 1965. Maki et al generalized α -closed sets to αg -closed sets [13] and αg -closed sets [15] in 1993 and 1994 respectively. Dontchev [16] (resp. Palaniappan and Rao [14], Gnanambal [18]) introduced gsp-closed (resp. rg-closed, gpr-closed) sets in 1995 (resp. 1993, 1997). Veera Kumar introduced \hat{g} -closed sets [22], ψ -closed sets [20], *g -closed sets [25], g^* -closed sets [21]. Manoj et al. introduced the concepts of \hat{g} -closed sets [24] in 2007.

In this paper we study relationships of \bar{g} -closed sets with the above mentioned sets.

Norman Levine [3], Bhattacharya and Lehiri [7] and Devi et al. [12] introduced $T_{1/2}$ -spaces, semi- $T_{1/2}$ spaces and T_b and T_d -spaces respectively. Devi et al [19] again introduce ${}_\alpha T_b$ -spaces and ${}_\alpha T_d$ -spaces. Veera Kumar introduced T_f -spaces [22], \hat{T}_b -spaces and ${}_\alpha \hat{T}_b$ -spaces [23], $T^*_{1/2}$ -spaces and ${}^*T_{1/2}$ -spaces [21]. Recently Manoj et al. [24] introduced \hat{T}_f -spaces.

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We introduce and study new classes of spaces, namely the class of \bar{T} -spaces, the class of \bar{T}^* -spaces and the class of ${}^*\bar{T}$ -spaces. Further we characterize and study some relationships of these spaces with the above defined spaces.

We also introduced \bar{g} -continuous maps, \bar{g} -irresolute maps and investigate some of their properties.

Throughout this paper (X, τ) , (Y, σ) and (Z, η) represent non-empty topological spaces on which no separation axioms are assumed unless or otherwise mentioned. For a subset A of a space (X, τ) , $cl(A)$, $int(A)$, $pcl(A)$ and A^c denote the closure of A, the interior of A, pre-closure of A and the complement of A respectively.

Preliminaries

We recall the following definitions which are useful in the sequel.

Definition: A subset A of a topological space (X, τ) is called semi-open [1] (resp. semi-closed, pre-open [5], pre-closed, α -open [2], α -closed, semi-preopen [6], semi-pre closed, regular open [28], regular closed) if $A \subseteq cl(int(A))$ (resp. $int(cl(A)) \subseteq A$, $A \subseteq int(cl(A))$, $cl(int(A)) \subseteq A$, $A \subseteq int(cl(int(A)))$, $cl(int(cl(A))) \subseteq A$, $A \subseteq cl(int(cl(A)))$, $int(cl(int(A))) \subseteq A$, $A = int(cl(A))$, $A = cl(int(A))$).

Definition: A subset A of a topological space (X, τ) is called g-closed [3] (resp. sg-closed[7], gs-closed[8], $g\alpha$ -closed [13], αg -closed [15], rg-closed [14], gpr-closed [18], gsp-closed [16], \hat{g} -closed [22], ψ -closed [20], *g -closed [25], \hat{g} -closed

[24], g^* -closed [21], *gs -closed [26], $\#gs$ -closed [27]) if $cl(A) \subseteq U$ (resp. $scl(A) \subseteq U$, $scl(A) \subseteq U$, $\alpha cl(A) \subseteq U$, $\alpha cl(A) \subseteq U$, $cl(A) \subseteq U$, $pcl(A) \subseteq U$, $spcl(A) \subseteq U$, $cl(A) \subseteq U$, $scl(A) \subseteq U$, $cl(A) \subseteq U$, $cl(A) \subseteq U$, $scl(A) \subseteq U$, $scl(A) \subseteq U$) whenever $A \subseteq U$ and U is open (resp. semi-open, open, α -open, open, regular open, regular open, open, semi-open, sg -open, \hat{g} -open, sg -open, g -open, \hat{g} -open, *g -open) in (X, τ) .

The complement of a g -closed (resp. \hat{g} -closed, $\hat{\hat{g}}$ -closed, *g -closed) set is called g -open (resp. \hat{g} -open, $\hat{\hat{g}}$ -open, *g -open) set.

Definition: A function $f: (X, \tau) \rightarrow (Y, \sigma)$ is called g -continuous [10] (resp. sg -continuous [11], gs -continuous [17], αg -continuous [18], rg -continuous [14], gpr -continuous [18], gsp -continuous [16], *g -continuous [23], g^* -continuous [21], \hat{g} -continuous [23], $\hat{\hat{g}}$ -continuous [24], semi-continuous [1], irresolute [4], gc -irresolute [10], sg -irresolute [11], \hat{g} -irresolute [23], $\hat{\hat{g}}$ -irresolute [24], *g -irresolute [25]) if $f^{-1}(V)$ is g -closed (resp. sg -closed, gs -closed, αg -closed, rg -closed, gpr -closed, gsp -closed, *g -closed, g^* -closed, \hat{g} -closed, $\hat{\hat{g}}$ -closed, semi-closed, semi-closed, gc -closed, sg -closed, \hat{g} -closed, $\hat{\hat{g}}$ -closed, *g -closed) set in (X, τ) for every closed (resp. closed, semi-closed, gc -closed, sg -closed, \hat{g} -closed, $\hat{\hat{g}}$ -closed, *g -closed) set in (Y, σ) .

Definition: A space (X, τ) is called $T_{1/2}$ [3] (resp. T_b [12], T_d [12], ${}_{\alpha}T_b$ [19], ${}_{\alpha}T_d$ [19], semi- $T_{1/2}$ [7], T_f [22], \hat{T}_b [23], $T^*_{1/2}$ [21], ${}^*T_{1/2}$ [21], \hat{T}_f [24]) space if every g -closed (resp. gs -closed, gs -closed, αg -closed, αg -closed, sg -closed, g -closed, gs -closed, g^* -closed, g -closed, g -closed) set is a closed (resp. closed, g -closed, closed, g -closed, semi-closed, \hat{g} -closed, $\hat{\hat{g}}$ -closed, closed, closed, g^* -closed, $\hat{\hat{g}}$ -closed) set in (Y, σ) .

Basic properties of \bar{g} -closed sets

In this section we study the relationship of \bar{g} -closed sets with other sets.

Definition: A subset A of topological (X, τ) is called \bar{g} -closed set if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is a $\hat{\hat{g}}$ -open set in (X, τ) .

The complement of \bar{g} -closed set is called \bar{g} -open set.

Theorem:

1. Every closed (or *g -closed or g^* -closed or $\hat{\hat{g}}$ -closed) set is \bar{g} -closed set.
2. Every \bar{g} -closed set is αg -closed (or g -closed or rg -closed or gpr -closed or gs -closed) set.

Next examples show that converse of the above theorem is not true in general.

Example: Let $X = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, \{a, b\}, X\}$. Consider $A = \{a, c\}$ then A is not a closed set. However A is \bar{g} -closed set. The set $B = \{b, c\}$ is αg -closed, rg -closed, gpr -closed and gs -closed set. However B is not a \bar{g} -closed set.

Example: Let $X = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, \{b, c\}, X\}$. Consider $A = \{b\}$ then A is not a *g -closed set and g^* -closed set. However A is a \bar{g} -closed set. The set $B = \{a, b\}$ is not a $\hat{\hat{g}}$ -closed set. However it is \bar{g} -closed set.

Therefore the class of \bar{g} -closed sets is properly contained in the class of g -closed sets, the class of αg -closed sets, the class of rg -closed sets, the class of gpr -closed sets, the class of gs -closed sets. Also this new class is properly contains the class of closed sets, the class of *g -closed sets, the class of g^* -closed sets and the class of $\hat{\hat{g}}$ -closed sets.

Remark: \bar{g} -closed set is independent from semi-closed sets, sg -closed sets, α -closed sets, ψ -closed sets, $\#gs$ -closed sets and *gs -closed sets.

The following examples support the above results.

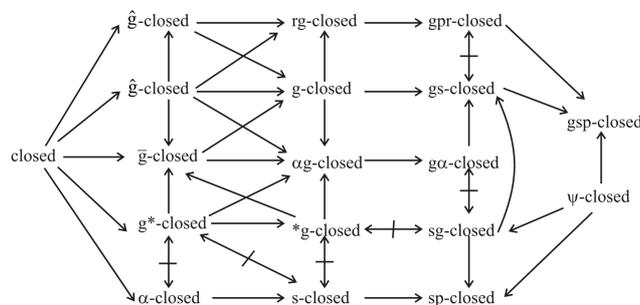
Example: Let $X = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, X\}$. Consider $A = \{a, b\}$, then A is not a semi-closed set. However A is \bar{g} -closed set. The set $B = \{a, b\}$ is a \bar{g} -closed set but not sg -closed, ψ -closed and $\#gs$ -closed sets.

Example: Let $X = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, \{c\}, \{a, c\}, X\}$. Consider $A = \{a\}$ then A is not a \bar{g} -closed set. However A is semi-closed set. The set $B = \{a\}$ is sg -closed, ψ -closed and $\#gs$ -closed set but not a \bar{g} -closed set.

Example: Let $X = \{a, b, c\}$, $\tau = \{\emptyset, \{b\}, \{b, c\}, X\}$. Consider $A = \{c\}$ then A is not a \bar{g} -closed set. However A is α -closed set. The set $B = \{a, b\}$ is not α -closed set. However B is \bar{g} -closed set.

Example: Let $X = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, \{b, c\}, X\}$. Consider $A = \{a, b\}$ then A is \bar{g} -closed set but not *gs -closed set.

The following diagram shows the relationships of \bar{g} -closed set with other sets.



Theorem: Intersection of two \bar{g} -closed sets is not necessarily \bar{g} -closed set.

The following example supports the above theorem.

Example: Let $X = \{a, b, c, d\}$, $\tau = \{\emptyset, \{a, b\}, X\}$. Consider $A = \{a, c\}$ and $B = \{a, d\}$ then A and B are \bar{g} -closed sets. However their intersection $\{a\}$ is not a \bar{g} -closed set.

Theorem: Union of two \bar{g} -closed sets is again a \bar{g} -closed sets.

Theorem: If A be a \bar{g} -closed set in a space (X, τ) and $A \subseteq B \subseteq \text{cl}(A)$ then B is also a \bar{g} -closed set.

Theorem: A is \bar{g} -closed set of (X, τ) if and only if $\text{cl}(A) - A$ does not contain any non-empty \hat{g} -closed set.

Applications of \bar{g} -closed sets

In this section we introduce the following definitions.

Definition: A topological space (X, τ) is called \bar{T} -space if every \bar{g} -closed set in it is cloed.

Definition: A topological space (X, τ) is called \bar{T}^* -space if every \bar{g} -closed set in it is $**g$ -closed set.

Theorem: Every T_b -space is \bar{T} -space.

The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.04), (X, τ) is \bar{T} -space but not T_b -space.

Theorem: Every \hat{T}_b -space is \bar{T} -space.

The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.04), (X, τ) is \bar{T} -space but not \hat{T}_b -space.

Theorem: Every \bar{T} -space is $\hat{T}_{1/2}$ -space.

The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.03), (X, τ) is $\hat{T}_{1/2}$ -space but not \bar{T} -space.

Theorem: Every $T_{1/2}$ -space (${}_{\alpha}T_b$ -space) is \bar{T} -space.

Theorem: Every \hat{T}_f -space is \bar{T}^* -space.

The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.03), (X, τ) is \bar{T}^* -space but not \hat{T}_f -space.

Theorem: Every $*T_{1/2}$ -space and so ${}^{\alpha}T_c$ -space is \bar{T}^* -space.

The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.03), (X, τ) is \bar{T}^* -space but not $*T_{1/2}$ -space.

Theorem: A topological space (X, τ) is $T_{1/2}$ -space iff it is \bar{T} -space and \bar{T}^* -space.

Theorem: Every \bar{T} -space is $T^*_{1/2}$ -space.

The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.02), (X, τ) is $T^*_{1/2}$ -space but not \bar{T} -space.

Theorem:Every ${}_{\alpha}T_b$ -space is \bar{T} -space.

Definition: A space (X, τ) is called $*\bar{T}$ -space if every αg -closed set is \bar{g} -closed.

Theorem: Every ${}_{\alpha}T_b$ -space is $*\bar{T}$ -space.

The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.02), (X, τ) is $*\bar{T}$ -space but not a ${}_{\alpha}T_b$ -space.

Theorem: Every $*\bar{T}$ -space is \bar{T}^* -space.

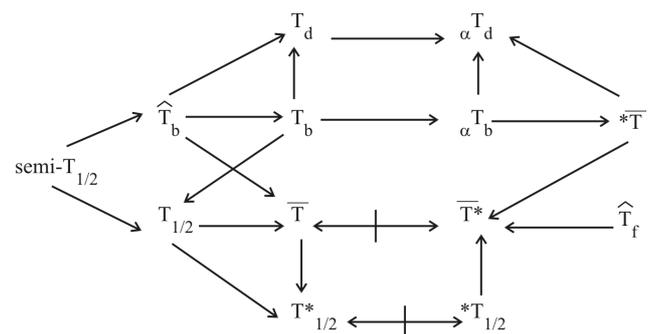
The converse of the above theorem is not true as it can be seen from the following example.

Example: In example (3.01), (X, τ) is \bar{T}^* -space but not a $*\bar{T}$ -space.

Theorem: Every $*\bar{T}$ -space is ${}_{\alpha}T_d$ -space.

Remark: \bar{T} -space and $*\bar{T}$ -space (or \bar{T}^* -space) are independent.

The following diagram shows the relationships between the separation axioms discussed in this section.



Theorem: If (X, τ) is $*\bar{T}$ -space then for each $x \in X$, $\{x\}$ is either αg -closed or $**g$ -closed.

Theorem: If (X, τ) is \bar{T}^* -space then for each $x \in X$, $\{x\}$ is either closed or $**g$ -closed.

Theorem: A topological space (X, τ) is \bar{T} -space iff every singleton of X is either \hat{g} -closed or open.

\bar{g} -continuous and \bar{g} -irresolute functions

In this section we introduce the following definitions.

Definition: A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be \bar{g} -continuous if the inverse image of every σ -closed set in Y is \bar{g} -closed in X .

Example: Let $X = \{a, b, c\}$ and $\tau = \{\emptyset, \{a\}, \{c\}, \{a, c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, X\}$. Define $f : (X, \tau) \rightarrow (X, \sigma)$ by identity mapping then f is \bar{g} -continuous mapping.

Definition: A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be \bar{g} -irresolute if the inverse image of every \bar{g} -closed set in Y is \bar{g} -closed in X .

Example: Let $X = \{a, b, c\}$ and $\tau = \{\phi, \{a\}, \{b, c\}, X\}$ and $\sigma = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by identity mapping then f is \bar{g} -irresolute mapping.

Theorem:

1. Every \bar{g} -irresolute map is \bar{g} -continuous map.
2. Every continuous map is \bar{g} -continuous map.
3. Every $*g$ -continuous (or g^* -continuous or \hat{g} -continuous) map is \bar{g} -continuous map.
4. Every \bar{g} -continuous map is αg -continuous (or rg -continuous or gpr -continuous or gs -continuous) map.
5. Every \bar{g} -continuous map is g -continuous (or $**gs$ -continuous) map.

The converse of the above theorem is not true as it can be seen from the following example.

Example: The function f in example (5.01) is \bar{g} -continuous but not \bar{g} -irresolute.

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{b\}, \{a, c\}, X\}$ and $\sigma = \{\phi, \{a\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = a$, $f(b) = b$ and $f(c) = c$ then f is \bar{g} -continuous but not continuous.

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{b, c\}, X\}$ and $\sigma = \{\phi, \{c\}, \{a, c\}, \{b, c\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = b$, $f(b) = a$ and $f(c) = c$ then f is \bar{g} -continuous but not $*g$ -continuous and \hat{g} -continuous.

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{a, b\}, X\}$ and $\sigma = \{\phi, \{a\}, \{a, b\}, \{a, c\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by identity map then f is αg -continuous, rg -continuous, gpr -continuous, gs -continuous and $**gs$ -continuous but not \bar{g} -continuous.

Therefore the class of \bar{g} -continuous maps properly contains the class of continuous maps, the class of $*g$ -continuous maps, the class of g^* -continuous maps and the class of \hat{g} -continuous maps and it is properly contained in the class of g -continuous maps, the class of αg -continuous maps, the class of rg -continuous maps, the class of gpr -continuous maps, the class of gs -continuous maps and the class of $**gs$ -continuous maps.

Remarks: The composition of two \bar{g} -continuous function need not be \bar{g} -continuous again. For consider the following example.

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$, $\sigma = \{\phi, \{b\}, X\}$ and $\eta = \{\phi, \{a\}, \{b, c\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = c$, $f(b) = b$ and $f(c) = a$. Define $g: (X, \sigma) \rightarrow (X, \eta)$ by $g(a) = c$, $g(b) = b$ and $g(c) = a$. then f and g are \bar{g} -continuous for $\{a\}$ is closed in (X, η) but $(g \circ f)^{-1}(\{a\}) = f^{-1}(g^{-1}(\{a\})) = f^{-1}(\{c\}) = \{a\}$ is not a \bar{g} -closed set in (X, τ) . Hence $g \circ f$ is not a \bar{g} -continuous.

Theorem: The composition of two \bar{g} -irresolute function is again \bar{g} -irresolute.

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an irresolute and closed then A is \bar{g} -closed in (X, τ) implies $f(A)$ is \bar{g} -closed in (Y, σ) .

Remarks: \bar{g} -continuity and semi-continuity are independent as seen from the following examples.

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, X\}$ and $\sigma = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = a$, $f(b) = c$ and $f(c) = b$. Then f is not a semi-continuous. However f is \bar{g} -continuous.

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$ and $\sigma = \{\phi, \{a\}, \{a, b\}, \{a, c\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by identity mapping. Then f is not a \bar{g} -continuous. However f is semi-continuous.

Remarks: \bar{g} -continuity and sg -continuity (or ψ -continuity or $\#gs$ -continuity) are independent as seen from the following examples.

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$ and $\sigma = \{\phi, \{a\}, \{c\}, \{a, b\}, \{a, c\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by identity mapping then f is not a \bar{g} -continuous, however f is sg -continuous (or ψ -continuous or $\#gs$ -continuous).

Example: Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, X\}$ and $\sigma = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$. Define $f: (X, \tau) \rightarrow (X, \sigma)$ by identity mapping. Then f is \bar{g} -continuous but not sg -continuous (or ψ -continuous or $\#gs$ -continuous).

Theorem: If $f: (X, \tau) \rightarrow (Y, \sigma)$ is \bar{g} -continuous and Y is T_u -space then f is \bar{g} -irresolute.

Theorem: Let (X, τ) , (Y, σ) and (Z, η) be any three topological spaces. Let $f: (X, \tau) \rightarrow (Y, \sigma)$ and $g: (Y, \sigma) \rightarrow (Z, \eta)$ be any two functions then $g \circ f: (X, \tau) \rightarrow (Z, \eta)$ is

1. \bar{g} -continuous if g is continuous and f is \bar{g} -continuous.
2. \bar{g} -irresolute if g is \bar{g} -irresolute and f is \bar{g} -irresolute.
3. \bar{g} -continuous if g is \bar{g} -continuous and f is \bar{g} -irresolute.
4. g -continuous if g is \bar{g} -continuous and f is g -irresolute.

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a \bar{g} -continuous map. If (X, τ) is T_u -space then f is continuous.

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an αg -continuous map. If (X, τ) is ${}_aT_u$ -space then f is \bar{g} -continuous.

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a g -continuous map. If (X, τ) is T_u^* -space then f is \bar{g} -continuous.

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be onto, \bar{g} -irresolute and closed map. If (X, τ) is T_u -space then (Y, σ) is also a T_u -space.

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be \hat{g} -irresolute and closed map. Then $f(A)$ is a \bar{g} -closed set of (Y, σ) for every \bar{g} -closed set A of (X, τ) .

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be onto, g -irresolute and pre- \bar{g} -closed map. If (X, τ) is \bar{T}^* -space then (Y, σ) is also a \bar{T}^* -space.

Theorem: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be onto, αg -irresolute and pre- \bar{g} -closed map. If (X, τ) is ${}^*\bar{T}$ -space then (Y, σ) is also a ${}^*\bar{T}$ -space.

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